



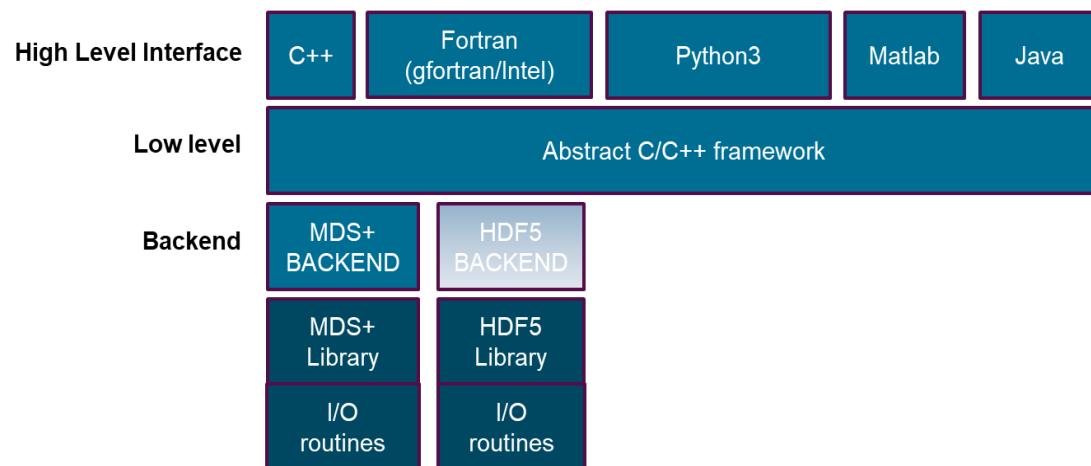
DE LA RECHERCHE À L'INDUSTRIE

High Level Interfaces & their Application Programming Interface

L. Fleury

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- The IMAS Data Access Layer exposes a couple of operations (so-called **API**) for writing/reading IDSs data
- These data access operations are available from users code in the currently supported programming languages, the so-called **High Level Interfaces (HLI)**:
 - Fortran
 - C++
 - Java
 - Python3
 - Matlab



- The **HLI API** can be divided into 2 sets of operations:
 - operations which apply on a **Data Entry**
 - operations which apply on an **IDS**
- A **Data Entry** is an IMAS concept for designating a collection of IDSs present in a local (pulse file) or a remote data source. A Data Entry is associated to a shot and a run number.
- The **HLI API** covers all available Access Layer features with the following exposed methods:

Operations on a Data Entry:

CREATE	(creates a new Data Entry)
OPEN	(opens an existing Data Entry)
CLOSE	(closes a Data Entry)

Operations on an IDS:

PUT	(writes data from an IDS to a Data Entry)
GET	(reads data of an IDS from an existing Data Entry)
PUT_SLICE	(writes a IDS time slice to a Data Entry)
GET_SLICE	(reads a time slice of an IDS from an existing Data Entry)
DELETE	(deletes an IDS from an existing Data Entry)

- In the online tutorial, each HLI API method is described using short code examples
- Code examples are using the Python **HLI**
- Provided Python3 programs can be executed interactively in a Python3 session or executed in a .py file
- API functions name and their signature may differ from one HLI to another
 - Documentation of all others HLIs is available in the User guide available from this page: <https://confluence.iter.org/display/IMP/Integrated+Modelling+Home+Page>

- The creation of a new Data Entry using the MDS+ or the HDF5 backend:
 - Consists in creating a new (MDS+/HDF5) pulse file on the disk
 - Requires to have at least an existing 'database' for hosting pulse file(s)
1. Let's first **create a new database** named 'data_access_tutorial' which will belong to the current user.
From a new shell, execute the following commands:

```
>module load IMAS  
>imasdb data_access_tutorial
```

The database is associated with a directory, let's **check** the latter has been successfully created by 'imasdb':

```
<g2lfleur@s52 ~>ls -alh ~/public/imasdb/data_access_tutorial  
total 6.0K  
drwxr-xr-x 3 g2lfleur g2itmdev 2.0K Sep 16 13:29 .  
drwxr-xr-x 5 g2lfleur g2itmdev 2.0K Sep 16 13:29 ..  
drwxr-xr-x 12 g2lfleur g2itmdev 2.0K Sep 16 13:29 3
```

2. Calling create() on an new Data Entry:

```
1. import imas  
   from imas import imasdef
```

In this example, the MDS+ pulse file is created then closed.
However no data have been yet saved to the pulse file.

```
2. #creating the Data Entry object 'data_entry' which handles the pulse file with  
shot=15000, run=1, belonging to database 'data_access_tutorial' of the current user,  
using the MDS+ backend  
data_entry = imas.DBEntry(imasdef.MDSPLUS_BACKEND, 'data_access_tutorial', 15000, 1)
```

```
3. #creating the pulse file handled by the Data Entry previously created  
data_entry.create()
```

```
#now, we could perform some write operations using the put() operation  
#... This will be dealt with later
```

```
4. #closing the Data Entry  
data_entry.close()
```

```
<g2lfleur@s52 ~>ls -alh ~/public/imasdb/data_access_tutorial/3/0/  
total 78M  
drwxr-xr-x 2 g2lfleur g2itmdev 2.0K Sep 16 15:28 .  
drwxr-xr-x 12 g2lfleur g2itmdev 2.0K Sep 16 13:29 ..  
-rw-r--r-- 1 g2lfleur g2itmdev 42M Sep 16 15:28 ids_150000001.characteristics  
-rw-r--r-- 1 g2lfleur g2itmdev 0 Sep 16 15:28 ids_150000001.datafile  
-rw-r--r-- 1 g2lfleur g2itmdev 36M Sep 16 15:28 ids_150000001.tree
```

The following code opens the existing MDS+ pulse file created previously for shot=15000, run=1, from the 'data_access_tutorial' database of the current user:

1.

```
import imas
from imas import imasdef
```
2.

```
#creating the Data Entry object 'data_entry' which handles the pulse file with shot=15000,
run=1, belonging to database 'data_access_tutorial' of the current user, using the MDS+ backend
data_entry = imas.DBEntry(imasdef.MDSPLUS_BACKEND, 'data_access_tutorial', 15000, 1)
```
3.

```
#opening the pulse file handled by the Data Entry previously created
data_entry.open()
```

#now, we could perform some read/write operations using the get/put() operations
#... This will be dealt with later
4.

```
#closing the Data Entry
data_entry.close()
```

Each IDS exposes the `get()` operation which reads **all** IDS data from an opened Data Entry.
 When calling the `get()` operation on a IDS, **all** scalars and data arrays contained in the IDS are read.
 All these data are put in memory.

ITER Physics Data Model Documentation for magnetics

Full path name	Description	Data Type	Coordinates																					
» ids_properties	Interface Data Structure properties. This element identifies the node above as an IDS	structure																						
▼ flux_loop(i1)	Flux loops; partial flux loops can be described	struct_array [max_size=200 (limited in MDS+ backend only)]	1- 1...N																					
name	Name of the flux loop {static}	STR_0D																						
identifier	ID of the flux loop {static}	STR_0D																						
» type	Flux loop type. Available options (refer to the children of this identifier structure) :	structure																						
	<table border="1"> <thead> <tr> <th>Name</th> <th>Index</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>toroidal</td> <td>1</td> <td>Toroidal flux loop</td> </tr> <tr> <td>saddle</td> <td>2</td> <td>Saddle loop</td> </tr> <tr> <td>diamagnetic_internal</td> <td>3</td> <td>Diamagnetic internal loop</td> </tr> <tr> <td>diamagnetic_external</td> <td>4</td> <td>Diamagnetic external loop</td> </tr> <tr> <td>diamagnetic_compensation</td> <td>5</td> <td>Diamagnetic compensation loop</td> </tr> <tr> <td>diamagnetic_differential</td> <td>6</td> <td>Diamagnetic differential loop</td> </tr> </tbody> </table>	Name	Index	Description	toroidal	1	Toroidal flux loop	saddle	2	Saddle loop	diamagnetic_internal	3	Diamagnetic internal loop	diamagnetic_external	4	Diamagnetic external loop	diamagnetic_compensation	5	Diamagnetic compensation loop	diamagnetic_differential	6	Diamagnetic differential loop		
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diamagnetic_differential	6	Diamagnetic differential loop																						
» position(i2)	List of (R,Z,phi) points defining the position of the loop (see data structure documentation FLUXLOOPPosition.pdf) {static}	struct_array [max_size=10 (limited in MDS+ backend only)]	1- 1...N																					
indices_differential()	Indices (from the flux_loop array of structure) of the two flux loops used to build the flux difference flux(second index) - flux(first index). Use only if ./type/index = 6, leave empty otherwise {static}	INT_1D	1- 1...2																					
area	Effective area (ratio between flux and average magnetic field over the loop) {static} [m^2]	FLT_0D																						
gm9	Integral of 1/R over the loop area (ratio between flux and magnetic rigidity R0 B0). Use only if ./type/index = 3 to 6, leave empty otherwise. {static} [m]	FLT_0D																						
▼ flux	Measured magnetic flux over loop in which Z component of normal to loop is directed downwards (negative grad Z direction) [Wb]. This quantity is COCOS-dependent, with the following transformation :	structure																						
	<table border="1"> <thead> <tr> <th>Label</th> <th>Expression</th> </tr> </thead> <tbody> <tr> <td>psi_like</td> <td>fact_psi</td> </tr> </tbody> </table>	Label	Expression	psi_like	fact_psi																			
Label	Expression																							
psi_like	fact_psi																							
data()	Data (dynamic) {as_parent}	FLT_1D	1- flux_loop(i1) flux/time																					
validity_timed()	Indicator of the validity of the data for each time slice. 0: valid from automated processing, 1: valid and certified by the diagnostic RO; -1 means problem identified in the data processing (request verification by the diagnostic RO), -2: invalid data, should not be used (values lower than -2 have a code-specific meaning detailing the origin of their invalidity) {dynamic}	INT_1D	1- flux_loop(i1) flux/time																					
validity	Indicator of the validity of the data for the whole acquisition period. 0: valid from automated processing, 1: valid and certified by the diagnostic RO; -1 means problem identified in the data processing (request verification by the diagnostic RO), -2: invalid data, should not be used (values lower than -2 have a code-specific meaning detailing the origin of their invalidity) {constant}	INT_0D																						
time()	Time (dynamic) [s]	FLT_1D	1- 1...N																					

The code below reads an existing 'magnetics' IDS from a WEST pulse file:

1. #opening the existing Data Entry from WEST

```
data_entry = imas.DBEntry(imasdef.MDSPLUS_BACKEND, 'west', 54178, 0, 'g2lfleur')
```

(see code in a previous slide for completing this step)

2. #reading the 'magnetics' IDS from the Data Entry previously opened

```
magnetics_ids = data_entry.get('magnetics', 0) #argument 0 is the so-called IDS occurrence
```

3. #closing the Data Entry

```
data_entry.close()
```

```
#printing some IDS attributes
```

```
print('Number of flux loops = ', len(magnetics_ids.flux_loop))
```

```
print('First flux loop = ', magnetics_ids.flux_loop[0].flux.data)
```

```
print('Time basis = ', magnetics_ids.time)
```

Output:

```
Number of flux loops = 17
```

```
First flux loop = [ 0.00065229  0.00163073  0.00489218... -0.01761185 -0.01663342 -0.01500269]
```

```
Time basis = [ 1.83570397  1.86847198  1.90123999 ... 90.13289642 90.16566467 90.19843292]
```

In order to write **all** data (scalars and data arrays) contained in an IDS to the pulse file created previously, we will call the `put()` operation which writes all static (non time dependent) AND dynamic data present in the IDS.

1. #opening the existing Data Entry (shot=15000, run=1)
(see code in a previous slide)
 2. #creating a new 'magnetics' IDS
`magnetics_ids = imas.magnetics()`
 3. #populating the 'magnetics' IDS
`magnetics_ids.ids_properties.homogeneous_time=1` #setting the homogeneous time (mandatory)
`magnetics_ids.ids_properties.comment='IDS created for testing the IMAS Data Access layer'`
`magnetics_ids.flux_loop[0].flux.data = numpy.array([10,12,13.5,15])` #using some fancy values...
`magnetics_ids.time=numpy.array([0,1,2,3])` #the time(vector) must be not empty if
homogeneous_time==1 otherwise an error will occur at runtime
 4. #writing the magnetics IDS to the Data Entry
`data_entry.put(magnetics_ids, 0)` #argument 0 is the so-called IDS occurrence
 5. #closing the Data Entry
`data_entry.close()`
- An example of mixing `get()/put()` using 2 different Data Entries is given in the online tutorial

An IDS containing dynamic data structures can be built progressively using time slices.

A dynamic data structure is either:

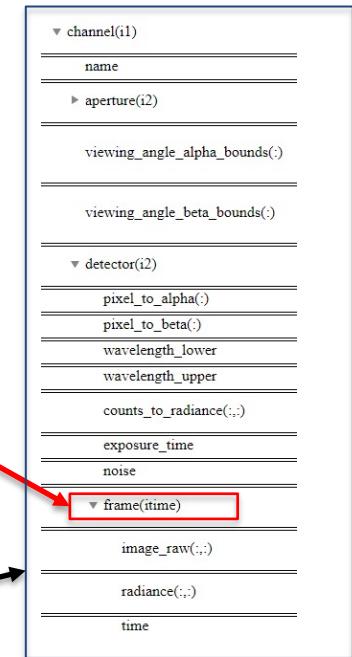
- an array with type INT_nD or FLT_nD where n=1 to 6, which holds a time coordinate
- or a so-called dynamic array of structures AOS[itime] where itime runs along a time index

In the online tutorial example, we illustrate the use of `put_slice()` on a 'camera_visible' IDS which contains the dynamic array of structures 'frame' (`camera_visible_ids.channel[0].detector[0].frame`).

Steps for building an IDS using time slices consist in:

1. opening an existing Data Entry (or creating a new one)
2. creating and initializing an IDS with static data
3. **setting the time slices container(s)**
4. **populating & writing time slices**
5. closing the Data Entry

Extract of the ITER Physics Data Model
Documentation for 'camera_visible' IDS



```
3. #setting time slices container(s) (camera_visible_ids.channel[0].detector[0].frame[0])
camera_visible_ids.channel.resize(1) #using only 1 channel (channel 0) for this example
camera_visible_ids.channel[0].detector.resize(1) #using only 1 detector for channel 0
camera_visible_ids.channel[0].detector[0].frame.resize(1) #it is the slice to be appended to the IDS
X = 3 #number of horizontal pixels of 2D ‘image_raw’ field
Y = 5 #number of vertical pixels of 2D ‘image_raw’ field
camera_visible_ids.channel[0].detector[0].frame[0].image_raw.resize(X,Y) #setting the size of the image
camera_visible_ids.time.resize(1) #the time vector contains only 1 element, it’s the time of the slice
```

4. #populating & writing time slices

```
nb_slices=3 #number of time slices to be added
```

```
for i in range(nb_slices):
    camera_visible_ids.time[0] = float(i) #setting the time of the slice
    for j in range(X):
        for k in range(Y):
            #image_raw is a 2D array containing an image of X*Y pixels
            camera_visible_ids.channel[0].detector[0].frame[0].image_raw[j,k] = float(j + k + i)
if i==0:
    data_entry.put(camera_visible_ids) #the first slice i=0 has to be added using put()
else:
    data_entry.put_slice(camera_visible_ids) #appending current slice to the IDS using put_slice()
```

Only time slices of the 2D image_raw field of the first detector of the first channel are populated in this example:

```
camera_visible_ids.channel[0].detector[0].frame[0].image_raw
```

Content of 'camera_visible' IDS:
 (running previous code example using put_slice)

Slice time : 0.0	Slice time : 1.0	Slice time : 2.0
Image raw:	Image raw:	Image raw:
[[0 1 2 3 4]	[[1 2 3 4 5]	[[2 3 4 5 6]
[1 2 3 4 5]	[2 3 4 5 6]	[3 4 5 6 7]
[2 3 4 5 6]]	[3 4 5 6 7]]	[4 5 6 7 8]]
-----	-----	-----

Getting a time slice of 'camera_visible' IDS

1. #opening the existing Data Entry
 (see code in a previous slide)
 2. #getting a slice of 'camera_visible' IDS at the specified time using the closest interpolation
`time_requested=1.`
- ```
slice = data_entry.get_slice('camera_visible', time_requested, imasdef.CLOSEST_INTERP, 0)
```

```
print("Slice time: ", time_requested)
print("Image raw:")
print(slice.channel[0].detector[0].frame[0].image_raw)
print("-----")
```

3. #closing the Data Entry  
`data_entry.close()`

**Result:**  
 (running this code)

| Slice time : 1.0 |
|------------------|
| Image raw:       |
| [[1 2 3 4 5]     |
| [2 3 4 5 6]      |
| [3 4 5 6 7]]     |
| -----            |